

HEP-CCE PPS Weekly Meeting – 29 January 2021

Introduction to alpaka

Jan Stephan <j.stephan@hzdr.de>



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Introduction to alpaka

Introduction to alpaka

alpaka – Abstraction Library for Parallel Kernel Acceleration



Alpaka is...

- ... a parallel programming library: Accelerate your code by exploiting your hardware's parallelism!
- ... an abstraction library: Create portable code that runs on CPUs, GPUs and FPGAs!
- ... free & open-source software

Introduction to alpaka

Programming with alpaka

- C++ only!
- Header-only library: No additional runtime dependency introduced
- Modern library: alpaka is written entirely in C++14 (transitioning to C++17 soon)
- Supports a wide range of modern C++ compilers (g++, clang++, Apple clang, MS Visual Studio)
- Portable across operating systems: Linux, macOS, Windows are supported



Basic concepts

- Full control for the user, everything is explicit
 - no hidden allocations, copies, ...
- Everything is a concept / trait (through C++ templates)
 - high degree of customization possible
- Abstractions are resolved at compile time
 - longer compilation time, but very close to native code performance
- CUDA inheritance: work division defined through grids, blocks, warps & threads
- Additional work division layer: data elements per thread (used for auto-vectorization)

AXPY

$$\vec{y} \leftarrow a \cdot \vec{x} + \vec{y}$$

```
using namespace alpaka;

struct AxyKernel
{
    template <typename TAcc>
    ALPAKA_FN_ACC void operator()(TAcc const& acc,
        std::size_t numElements, int a, int const* X, int* Y) const
    {
        auto gridThreadId = getIdx<Grid, Threads>(acc)[0u];
        auto threadElems = getWorkDiv<Thread, Elems>(acc)[0u];
        auto first = gridThreadId * threadElems;

        if(first < numElements)
        {
            auto last = first + threadElems;
            for(auto i = first; i < last; ++i)
                Y[i] = a * X[i] + Y[i];
        }
    }
};
```

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AXPY

```
using namespace alpaka;  
using Dim = DimInt<1u>;  
using Idx = std::size_t;  
using Acc = AccGpuCudaRt<Dim, Idx>;
```

$$\vec{y} \leftarrow \alpha \cdot \vec{x} + \vec{y}$$

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AXPY

```
using namespace alpaka;  
using Dim = DimInt<1u>;  
using Idx = std::size_t;  
using Acc = AccGpuCudaRt<Dim, Idx>;
```

```
auto const host = getDevByIdx<DevCpu>(0u);  
auto const dev = getDevByIdx<Acc>(0u);  
using myQueue = Queue<Acc, property::Blocking>;  
auto queue = myQueue{dev};
```

$$\vec{y} \leftarrow \alpha \cdot \vec{x} + \vec{y}$$

AXPY

$$\vec{y} \leftarrow \alpha \cdot \vec{x} + \vec{y}$$

```
using namespace alpaka;
using Dim = DimInt<1u>;
using Idx = std::size_t;
using Acc = AccGpuCudaRt<Dim, Idx>;

auto const host = getDevByIdx<DevCpu>(0u);
auto const dev = getDevByIdx<Acc>(0u);
using myQueue = Queue<Acc, property::Blocking>;
auto queue = myQueue{dev};

auto const ext = Vec<Dim, Idx>{1024};
auto hostBufX = allocBuf<int, Idx>(host, ext);
/* Initialize ... */
auto devBufX = allocBuf<int, Idx>(dev, ext);
```

AXPY

$$\vec{y} \leftarrow \alpha \cdot \vec{x} + \vec{y}$$

```
using namespace alpaka;
using Dim = DimInt<1u>;
using Idx = std::size_t;
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auto const host = getDevByIdx<DevCpu>(0u);
auto const dev = getDevByIdx<Acc>(0u);
using myQueue = Queue<Acc, property::Blocking>;
auto queue = myQueue{dev};

auto const ext = Vec<Dim, Idx>{1024};
auto hostBufX = allocBuf<int, Idx>(host, ext);
/* Initialize ... */
auto devBufX = allocBuf<int, Idx>(dev, ext);

memcpy(queue, devBufX, hostBufX, ext); // namespace alpaka
```

AXPY

$$\vec{y} \leftarrow a \cdot \vec{x} + \vec{y}$$

```
using namespace alpaka;
using Dim = DimInt<1u>;
using Idx = std::size_t;
using Acc = AccGpuCudaRt<Dim, Idx>;

auto const host = getDevByIdx<DevCpu>(0u);
auto const dev = getDevByIdx<Acc>(0u);
using myQueue = Queue<Acc, property::Blocking>;
auto queue = myQueue{dev};

auto const ext = Vec<Dim, Idx>{1024};
auto hostBufX = allocBuf<int, Idx>(host, ext);
/* Initialize ... */
auto devBufX = allocBuf<int, Idx>(dev, ext);

memcpy(queue, devBufX, hostBufX, ext);

auto workDiv = getValidWorkDiv<Acc>(dev, ext, Idx{1u});
auto taskKernel = createTaskKernel<Acc>(
    workDiv, AxyKernel{}, /* params ... */);
enqueue(queue, taskKernel);
```

AXPY

$$\vec{y} \leftarrow a \cdot \vec{x} + \vec{y}$$

```
using namespace alpaka;
using Dim = DimInt<1u>;
using Idx = std::size_t;
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auto const host = getDevByIdx<DevCpu>(0u);
auto const dev = getDevByIdx<Acc>(0u);
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auto queue = myQueue{dev};

auto const ext = Vec<Dim, Idx>{1024};
auto hostBufX = allocBuf<int, Idx>(host, ext);
/* Initialize ... */
auto devBufX = allocBuf<int, Idx>(dev, ext);

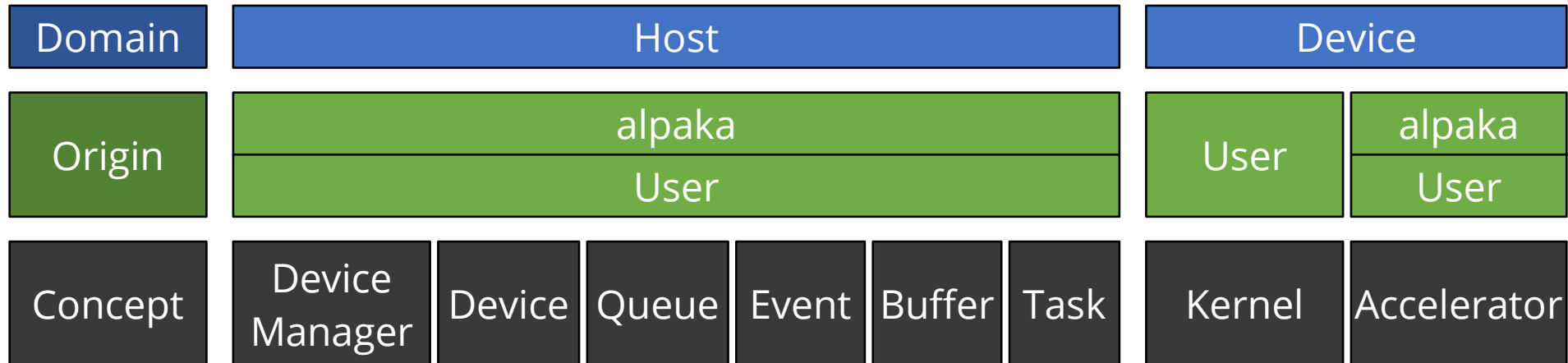
memcpy(queue, devBufX, hostBufX, ext);

auto workDiv = getValidWorkDiv<Acc>(dev, ext, Idx{1u});
auto taskKernel = createTaskKernel<Acc>(
    workDiv, AxyKernel{}, /* params ... */);
enqueue(queue, taskKernel);

memcpy(queue, hostBufX, devBufX, ext);
```

Introduction to alpaka

alpaka's structure



Vector addition: alpaka CUDA PTX

```
mov.u32    %r3, %ctaid.x;
mov.u32    %r4, %ntid.x;
mov.u32    %r5, %tid.x;
mad.lo.s32 %r1, %r4, %r3, %r5;
setp.ge.s32 %p1, %r1, %r2;
@%p1 bra  BB6_2;

cvta.to.global.u64 %rd3, %rd2;
cvta.to.global.u64 %rd4, %rd1;
mul.wide.s32      %rd5, %r1, 8;
add.s64          %rd6, %rd4, %rd5;
ld.global.f64    %fd2, [%rd6];
add.s64          %rd7, %rd3, %rd5;
ld.global.f64    %fd3, [%rd7];
fma.rn.f64      %fd4, %fd2, %fd1, %fd3;
st.global.f64    [%rd7], %fd4;
```

Vector addition: native CUDA PTX

```
mov.u32    %r3, %ctaid.x;
mov.u32    %r4, %ntid.x;
mov.u32    %r5, %tid.x;
mad.lo.s32 %r1, %r4, %r3, %r5;
setp.ge.s32 %p1, %r1, %r2;
@%p1 bra  BB6_2;

cvta.to.global.u64 %rd3, %rd2;
cvta.to.global.u64 %rd4, %rd1;
mul.wide.s32      %rd5, %r1, 8;
add.s64          %rd6, %rd4, %rd5;
ld.global.nc.f64 %fd2, [%rd6];
add.s64          %rd7, %rd3, %rd5;
ld.global.f64    %fd3, [%rd7];
fma.rn.f64      %fd4, %fd2, %fd1, %fd3;
st.global.f64    [%rd7], %fd4;
```

Introduction to alpaka

Supported platform	Supported hardware
NVIDIA CUDA	NVIDIA GPUs
AMD HIP	AMD GPUs
	NVIDIA GPUs
OpenMP	OpenMP \geq 2.0: x86, OpenPOWER, ARM
	OpenMP \geq 5.0: Offloading targets
OpenACC \geq 2.0	Offloading targets
SYCL (experimental)	oneAPI hardware (CPUs, GPUs, FPGAs)
	Xilinx FPGAs
Additional CPU backends	CPUs

alpaka is targeting advanced users!

- Template metaprogramming & specialization result in high degree of flexibility
- alpaka has a steep learning curve!
- Good knowledge of C++ templates required
- Explicitness leads to verbosity
- Example: Use alpaka kernels to speed up performance-critical sections of smaller programs
- Example: HPC experts provide an alpaka-based library of common algorithms to scientists

Introduction to alpaka

alpaka is free software (MPL 2.0). Find us on GitHub!

Our GitHub organization: <https://www.github.com/alpaka-group>

- Contains all alpaka-related projects, documentation, samples, ...
- New contributors welcome!

The library: <https://www.github.com/alpaka-group/alpaka>

- Full source code, issue tracker, installation instructions, examples, ...

Detailed YouTube video series: <https://bit.ly/33MYZSQ>

- Slides: https://www.github.com/alpaka-group/alpaka-workshop-slides/tree/200629_cern



If you use alpaka for your research, please cite one of the following publications:

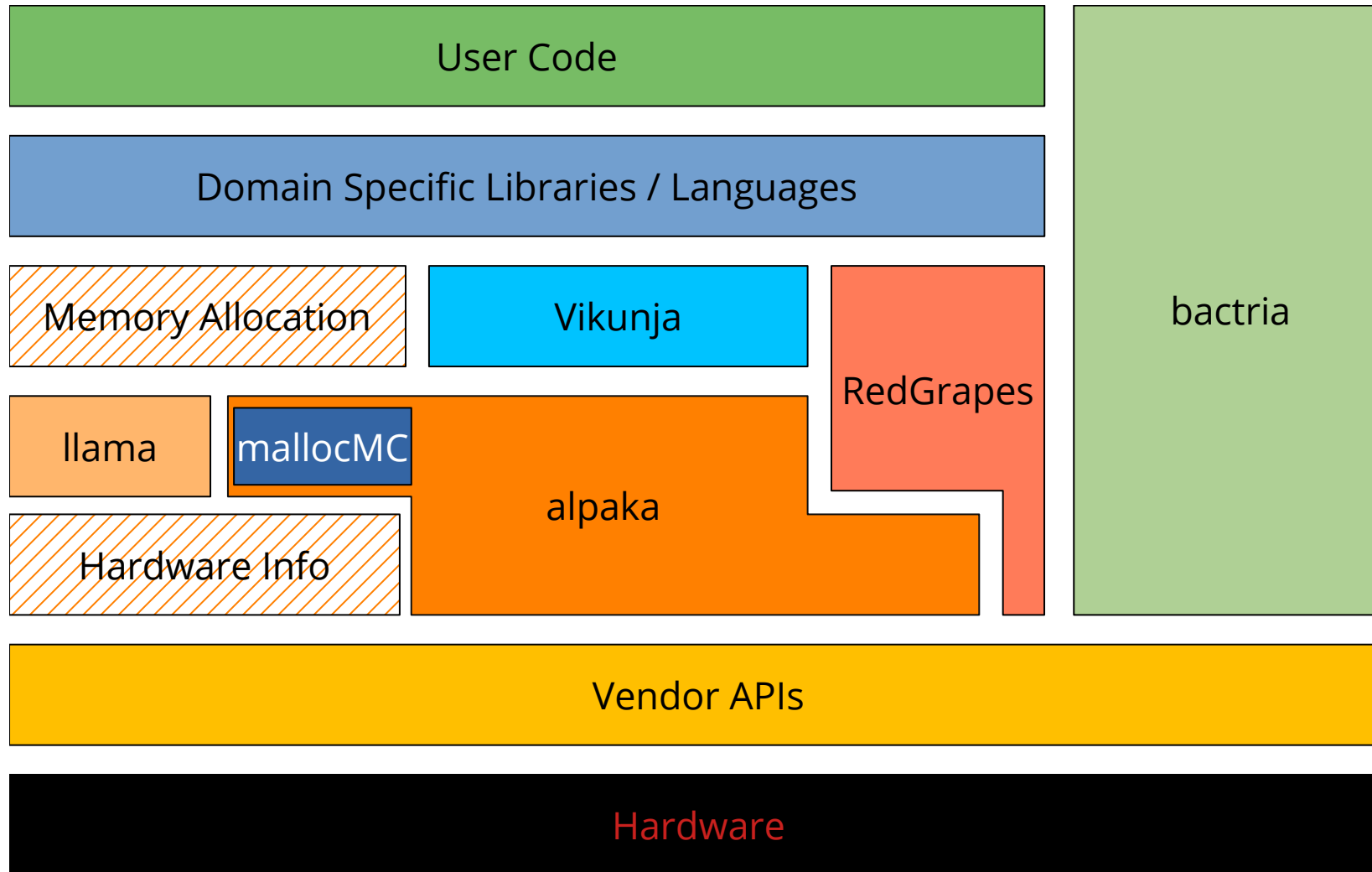
Matthes A., Widera R., Zenker E., Worpitz B., Huebl A., Bussmann M. (2017): Tuning and Optimization for a Variety of Many-Core Architectures Without Changing a Single Line of Implementation Code Using the Alpaka Library. In: Kunkel J., Yokota R., Taufer M., Shalf J. (eds) High Performance Computing. ISC High Performance 2017. Lecture Notes in Computer Science, vol 10524. Springer, Cham, DOI: [10.1007/978-3-319-67630-2_36](https://doi.org/10.1007/978-3-319-67630-2_36).

E. Zenker et al., “Alpaka – An Abstraction Library for Parallel Kernel Acceleration”, 2016 IEEE International Parallel and Distributed Processing Symposium Workshops (IPDPSW), Chicago, IL, 2016, pp. 631 – 640, DOI: [10.1109/IPDPSW.2016.50](https://doi.org/10.1109/IPDPSW.2016.50).


Worpitz, B. (2015, September 28). Investigating performance portability of a highly scalable particle-in-cell simulation code on various multi-core architectures. Zenodo. DOI: [10.5281/zenodo.49768](https://doi.org/10.5281/zenodo.49768).

alpaka's Ecosystem

The alpaka ecosystem



cupla - The CUDA portability layer



```
#include <cuda_runtime.h>

/* CUDA API calls */

kernel<<<blocks, threads>>>(/* params */);
```

```
#include <cuda_to_cupla.h>


/* CUDA API calls */

CUPLA_KERNEL(kernel)(blocks, threads)
    (/* params */);
```

- Use cupla (C++ User interface for the Platform independent Library Alpaka) to make existing CUDA codes portable!
- cupla maps CUDA API calls to the corresponding alpaka API calls

cupla - The CUDA portability layer

```
__global__ void kernel(/* params */)
{
    /* ... */
}
```



```
struct kernel
{
    template <typename TAcc>
    ALPAKA_FN_ACC
    void operator()(TAcc const& acc,
                   /* params */)
    {
        /* ... */
    }
};
```

- CUDA kernels need to be transformed into alpaka kernels
- Porting guide: <https://github.com/alpaka-group/cupla/blob/master/doc/PortingGuide.md>
- Tuning guide: <https://github.com/alpaka-group/cupla/blob/master/doc/TuningGuide.md>

cupla – The CUDA portability layer

cupla is free software (LGPL 3.0). Find us on GitHub!

The library: <https://www.github.com/alpaka-group/cupla>

- Full source code
- Issue tracker
- Installation instructions
- Small examples



Problem: representation of data is tied to physical layout

- Array of structs:

```
struct P { float x; float y; } p[8];  
p[i].x = 3.14f;  
func(p[i]);
```

- Struct of arrays:

```
struct P { float x[8]; float y[8]; } p;  
p.x[i] = 3.14f;  
func(p.x[i], p.y[i]);
```

- Changing the data layout requires changing the algorithm
- Different hardware needs different data layouts to perform well

LLAMA – Low Level Abstraction of Memory Access

Solution: Separate algorithmic data view and physical data layout

- LLAMA (Low Level Abstraction of Memory Access)
- Switch between memory layouts without touching the algorithm
- Header-only, portable C++17 library
- Supports CUDA ≥ 11
- Orthogonal to alpaka

LLAMA – Low Level Abstraction of Memory Access



```
struct Vec
{
    float x;
    float y;
    float z;
};

struct Particle
{
    Vec pos;
    Vec vel;
    float mass;
};
```

```
struct Pos{};
struct Vel{};
struct X{};
struct Y{};
struct Z{};
struct Mass{};

using Vec = llama:DS<
    llama::DE<X, float>,
    llama::DE<Y, float>,
    llama::DE<Z, float>>;

using Particle = llama::DS<
    llama::DE<Pos, Vec>,
    llama::DE<Vel, Vec>,
    llama::DE<Mass, float>>;
```

- LLAMA builds a tree of abstract tags
- Leaf elements carry final type used for computation

LLAMA – Low Level Abstraction of Memory Access

- Define problem size using `ArrayDomain`
- Compile-time dimensionality, runtime extents
- Choose desired memory mapping
 - LLAMA supports AoS, SoA and AoSoA mappings
- Allocate memory
 - LLAMA supports allocators based on `std::vector` (default), `std::shared_ptr` and stack memory
- Access data as needed
 - LLAMA provides a rich interface for accessing data

```
// Define problem size
llama::ArrayDomain domain{dimX, dimY};

// decltype(domain) is:
llama::ArrayDomain<2>;

// Choose Array-of-structs mapping
llama::mapping::AoS map{domain, Particle{}};

// Allocate memory with default allocator
auto view = llama::allocView(mapping);

// Access first particle
auto p = view(pos);

// Access particle information
float& x = p(Pos{}, X{});
```

LLAMA – Low Level Abstraction of Memory Access

LLAMA is free software (LGPL 3.0). Find us on GitHub!

LLAMA is a research prototype (but still useful)!

The library: <https://www.github.com/alpaka-group/llama>

Read the Docs: <https://llama-doc.rtf.d.io>

Doxygen: <https://alpaka-group.github.io/llama/>



Vikunja – Primitives for alpaka

Out now: Vikunja 0.1.0

- Vikunja provides high-level C++ primitives
 - reduce
 - transform
 - More on the way!
- Based on alpaka
- Get it here: <https://github.com/ComputationalRadiationPhysics/vikunja> (MPL 2.0)

Resource-based, Declarative task-Graphs for Parallel, Event-driven Scheduling

- Lightweight, application-level C++14 framework for creating and scheduling task graphs
- RedGrapes generates a task graph based on high-level resource descriptions and order of the code

- Get it here: <https://github.com/ComputationalRadiationPhysics/redGrapes> (MPL 2.0)
- Read the Docs: <https://redgrapes.rtf.d.io/>

Planning for the Future

Next alpaka Release

alpaka 0.7.0 – Expected later this year

- Improvement of kernel language
 - SIMD types
 - Abstraction of CUDA intrinsics
- Finalize SYCL back-end
 - mainline support for oneAPI hardware and Xilinx FPGAs
- More flexible memory abstraction

bactria – Profiling & Tracing Library

bactria – Broadly Applicable C++ Tracing and Instrumentation API

- Ongoing research project (still in early stages)
- Idea: Instrument portions of your code with a modern C++ API
- Choose desired profiling / tracing library at runtime and analyse output with your favourite tools!
- Monitor progress here: <https://github.com/alpaka-group/bactria> (EUPL 1.2)

Will alpaka support future technologies?

- alpaka's internal structure makes new back-ends easy to integrate
- Recent examples: new back-ends for HIP, OpenACC, SYCL (soon)

Will alpaka's ecosystem still be supported in 5, 10, 15, ... years?

Always in motion is the future. - Yoda

- Development funded by HZDR
- Developers active since ~2008
- Continuously expanding HPC software portfolio
- We are developing for our own science projects, too!

The End

alpaka



AMA



upla



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